

DISCRIMINATING AGAINST INTERFERENCE IN MASSIVE MIMO SYSTEMS: A STATISTICAL APPROACH

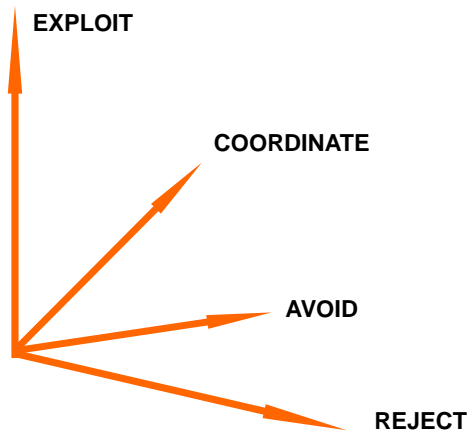
FUELING THE DENSE VS. MASSIVE DEBATE

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THE DIMENSIONS OF INTERFERENCE MANAGEMENT



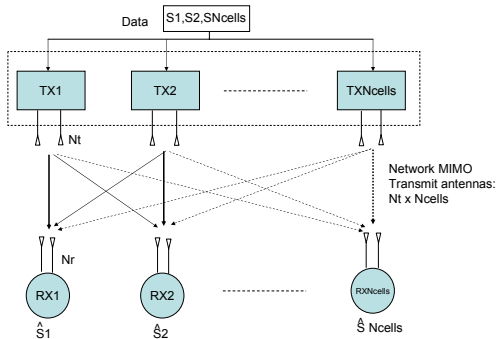
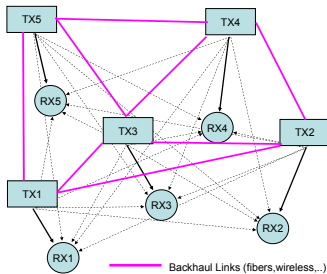
Transmitter cooperation involve substantial **information sharing**

- **Coordination**: transmitters exchange **CSIT**
 - Coordinated beamforming (CoMP in LTE-A), interference alignment, coordinated scheduling, coordinated power control..
- **Exploitation**: transmitters exchange **CSIT** and **user data**
 - Network (multicell) MIMO, Joint Processing CoMP
- **Rejection**: Simple per-terminal per-cell processing, little info exchange

Some questions:

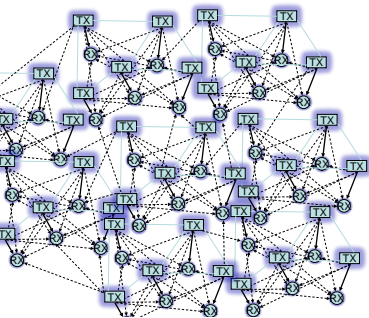
- Are such methods **scalable**?
- Do distributed implementation exist?

EXPLOITING INTERFERENCE VIA MULTICELL MIMO



THE "DENSE VS. MASSIVE" DEBATE

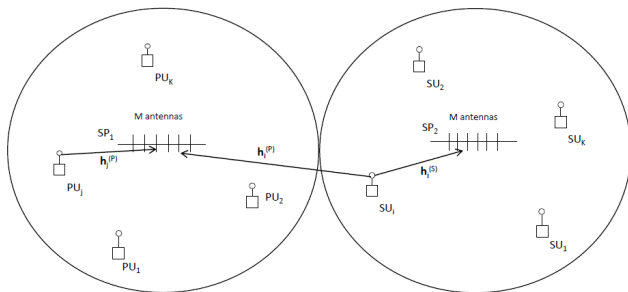
Dense cooperation (single antenna base station)



Massive MIMO base station (no cooperation)



WHAT CAN SIMPLE DISTRIBUTED BEAMFORMING ACHIEVE?



- Let M antennas be used at BS 1 and BS 2.
- As $M \rightarrow \infty$ (normalized) useful and interference channel vector become quasi **orthogonal**
- **Matched filter** maximizes SNR *and* cancels interference *simultaneously* [Marzetta 2010]
- Matched filter solution is **fully distributed!**

But there is a **problem**...

- Non orthogonal pilots -> pilot contamination (PC)
- PC destroys Massive MIMO theoretical benefits

Pilot sequence in l -th cell: $\mathbf{s}_l = [s_{l1} \quad s_{l2} \quad \cdots \quad s_{l\tau}]^T$
the $M \times \tau$ signal at the target base station (with noise \mathbf{N}) is

$$\mathbf{Y} = \sum_{l=1}^L \mathbf{h}_l \mathbf{s}_l^T + \mathbf{N} \quad (1)$$

Least Squares (LS) estimator with full pilot reuse:

$$\hat{\mathbf{h}}_1^{\text{LS}} = \mathbf{h}_1 + \sum_{l \neq 1}^L \mathbf{h}_l + \mathbf{N} \mathbf{s}_1^* / \tau \quad (2)$$

A MORE POWERFUL ESTIMATOR (WELL KNOWN!)

$$p(\mathbf{h}|\mathbf{y}) = \frac{\exp\left(-\left(\mathbf{h}^H \mathbf{R}^{-1} \mathbf{h} + (\mathbf{y} - \mathbf{S}\mathbf{h})^H (\mathbf{y} - \mathbf{S}\mathbf{h}) / \sigma_n^2\right)\right)}{AB}$$

where

$$\mathbf{R} \triangleq \text{diag}(\mathbf{R}_1, \dots, \mathbf{R}_L) \quad (3)$$

$A \triangleq (\pi \sigma_n^2)^{M\tau}$ and

$$B \triangleq \pi^{LM} (\det \mathbf{R})^M \quad (4)$$

Develop covariance-based (Bayesian or MMSE) estimator

$$\hat{\mathbf{h}}_1 = \mathbf{R}_1 \left(\sigma_n^2 \mathbf{I}_M + \tau \sum_{l=1}^L \mathbf{R}_l \right)^{-1} \mathbf{S}^H \mathbf{y} \quad (5)$$

\mathbf{R}_l is covariance matrix of l -th interference channel.

Theorem [Yin, Gesbert, Filippou, Liu JSAC 2013]

Assume multipath angle-of-arrival θ for user j (at target BS 1) has density $p_j(\theta)$ with bounded support, i.e. $p_j(\theta) = 0$ for $\theta \notin [\theta_j^{\min}, \theta_j^{\max}]$ for some fixed $\theta_j^{\min} \leq \theta_j^{\max} \in [0, \pi]$. If the $L - 1$ intervals $[\theta_i^{\min}, \theta_i^{\max}]$, $i = 2, \dots, L$ are strictly non-overlapping with $[\theta_1^{\min}, \theta_1^{\max}]$, we have

$$\lim_{M \rightarrow \infty} \hat{\mathbf{h}}_1 = \hat{\mathbf{h}}_1^{\text{no int}} \quad (6)$$

If desired and interference multipath ranges do no overlap, pilot contamination **vanish asymptotically**.

Classical specular channel model: $\mathbf{h}_i = \frac{1}{\sqrt{P}} \sum_{p=1}^P \mathbf{a}(\theta_{ip}) \alpha_{ip}$

where P is number of paths and

$$\mathbf{a}(\theta) \triangleq \begin{bmatrix} 1 \\ e^{-j2\pi \frac{D}{\lambda} \cos(\theta)} \\ \vdots \\ e^{-j2\pi \frac{(M-1)D}{\lambda} \cos(\theta)} \end{bmatrix} \quad (7)$$

Density function of random variable θ contains useful information, **captured by correlation matrix**.

$$\mathbf{R}_i = \frac{\delta_i^2}{P} \sum_{p=1}^P \mathbb{E}\{\mathbf{a}(\theta_{ip}) \mathbf{a}(\theta_{ip})^H\} = \delta_i^2 \mathbb{E}\{\mathbf{a}(\theta_i) \mathbf{a}(\theta_i)^H\}$$

Proof relies on three lemmas:

Lemma 1:

Define $\alpha(x) \triangleq [1 \quad e^{-j\pi x} \quad \dots \quad e^{-j\pi(M-1)x}]^T$. Given

$b_1, b_2 \in [-1, 1]$ and $b_1 < b_2$, define $\mathcal{B} \triangleq \text{span}\{\alpha(x) | x \in [b_1, b_2]\}$, then

- $\dim\{\mathcal{B}\} \sim (b_2 - b_1)M/2$ when M grows large.

lemma 2 *When M grows large,*

$$\text{rank}(\mathbf{R}_i) \leq d_i M$$

where

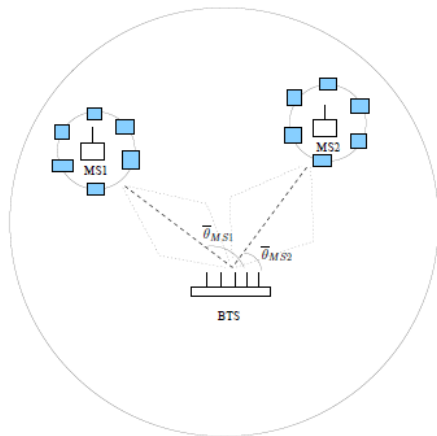
$$d_i \triangleq \left(\cos(\theta_i^{\min}) - \cos(\theta_i^{\max}) \right) \frac{D}{\lambda}$$

Lemma 1 indicates that for large M , there exists a null space $\text{null}(\mathbf{R}_i)$ of dimension $(1 - d_i)M$.

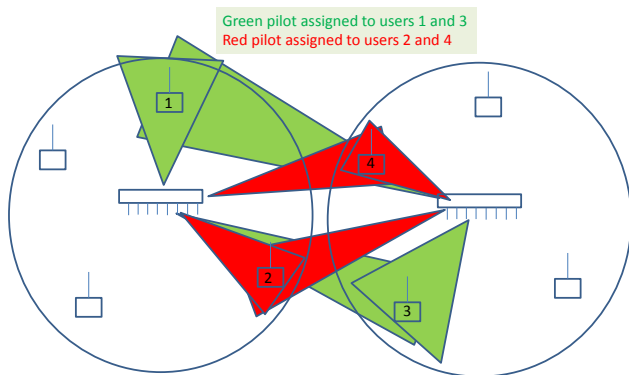
lemma 3 *When M is large, the null space $\text{null}(\mathbf{R}_i)$ includes the following set of unit norm vectors:*

$$\text{null}(\mathbf{R}_i) \supset \text{span} \left\{ \frac{\mathbf{a}(\Phi)}{\sqrt{M}}, \forall \Phi \notin [\theta_i^{\min}, \theta_i^{\max}] \right\}$$

LEARNING FROM COVARIANCE MATRICES



DECONTAMINATING PILOTS PUT TO PRACTICE



Coordinated Pilot Assignment (CPA):

- Estimate and exchange covariance information between cells (slow varying)
- Apply a coordinated pilot assignment based on covariance information to fulfill (almost) non-overlap condition between signal subspaces

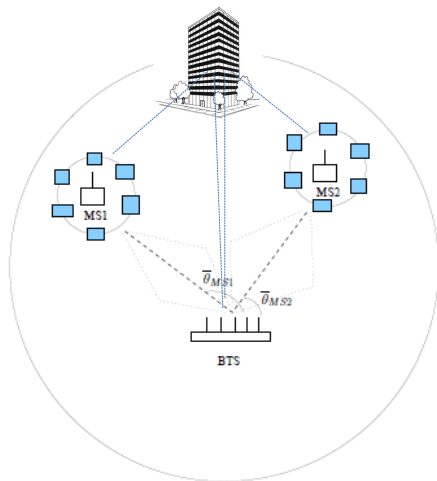
A given pilot sequence is assigned to a user set \mathcal{U} over L cells, minimizing a utility function

$$F(\mathcal{U}) \triangleq \sum_{j=1}^{|\mathcal{U}|} \frac{\mathcal{M}_j(\mathcal{U})}{\text{tr} \{ \mathbf{R}_{jj}(\mathcal{U}) \}} \quad (8)$$

where $\mathcal{M}_j(\mathcal{U})$ is the MSE for the desired channel at the j -th base station

- Use a greedy approach to avoid exhaustive search

THE SKYSCRAPER EFFECT



DECONTAMINATING PILOTS: PERFORMANCE

Angle spread 10 degrees

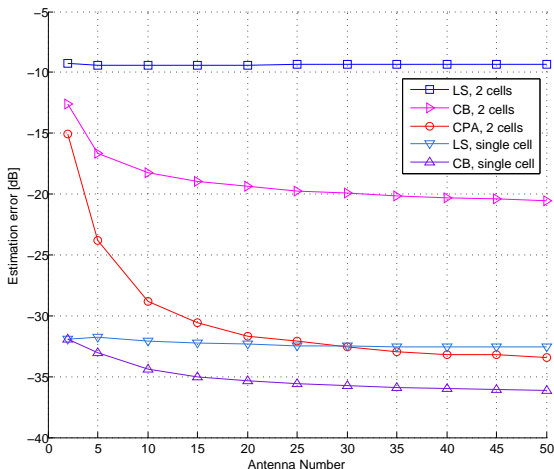


FIGURE: Estimation MSE vs. antenna number, Gaussian distributed AOAs with $\sigma = 10$ degrees.

10 Antennas

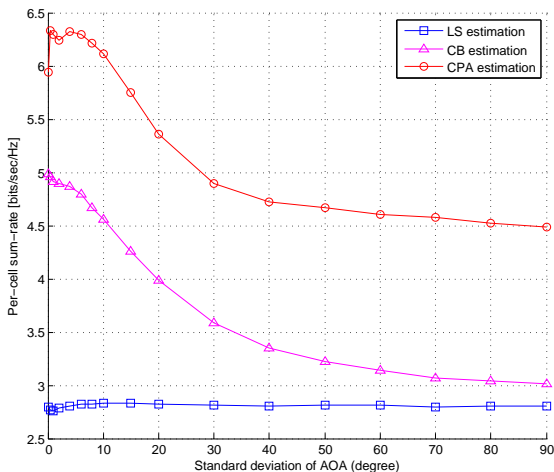


FIGURE: Per-cell sum-rate vs. standard deviation of AOA (Gaussian distribution) with $M = 10$, 7-cell network.

Uplink channel estimation with reused pilots:

$$\mathbf{Y} = \mathbf{h}_1 \mathbf{s}^T + \mathbf{h}_2 \mathbf{s}^T + \mathbf{N}, \quad (9)$$

Define the null space of \mathbf{R}_2 :

$$\mathbf{R}_2 = \mathbf{U}\Sigma\mathbf{U}^H \quad \mathbf{W}_1 = [\mathbf{u}_{m+1} | \mathbf{u}_{m+2} | \dots | \mathbf{u}_M]^H \quad (10)$$

Assume $\mathbf{h}_1 \in$ null space of \mathbf{R}_2 , then $\mathbf{h}_1 = \mathbf{W}_1^H \underline{\mathbf{h}}_1$ where $\underline{\mathbf{h}}_1$ is the effective channel. The subspace-based channel estimate is

$$\hat{\mathbf{h}}_1 = \mathbf{W}_1^H \hat{\underline{\mathbf{h}}}_1 = \mathbf{W}_1^H \mathbf{W}_1 \mathbf{Y} \mathbf{s}^* (\mathbf{s}^T \mathbf{s}^*)^{-1} \quad (11)$$

Note 1: One can also use the fact that $\mathbf{h}_1 \in$ signal subspace of \mathbf{R}_2 .

Note 2: These properties can be exploited for feedback reduction in FDD context (Adhikary, Caire 2012).

PERFORMANCE OF SUBSPACE-BASED ESTIMATION

Angle spread 30 degrees+random scheduler \Rightarrow very poor performance!

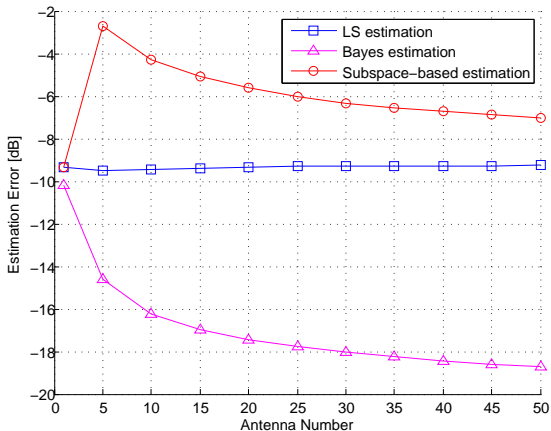


FIGURE: Estimation MSE vs. antenna number, uniformly distributed AOA's with $\theta_{\Delta} = 30$ degrees, 2-cell network.

Is it really necessary to have a good channel estimate? No!

Uplink received data:

$$\mathbf{y} = \mathbf{h}_1 \mathbf{s}_1^T + \mathbf{h}_2 \mathbf{s}_2^T + \mathbf{n}, \quad (12)$$

The subspace-based MRC beamformer is $\hat{\mathbf{h}}_1^H \mathbf{W}_1$

$$\hat{\mathbf{h}}_1^H \mathbf{W}_1 \mathbf{y} = \hat{\mathbf{h}}_1^H \mathbf{h}_1 \mathbf{s}_1^T + \underbrace{\hat{\mathbf{h}}_1^H \mathbf{W}_1 \mathbf{h}_2 \mathbf{s}_2^T}_{\approx \mathbf{0}} + \hat{\mathbf{h}}_1^H \mathbf{W}_1 \mathbf{n} \quad (13)$$

Subspace-based massive-MIMO beamformer yields **good** interference reduction signal enhancement trade-off...

SUBSPACE-BASED MRC BF: PERFORMANCE

Angle spread 30 degrees. **Worst channel estimate yields best data rate!**

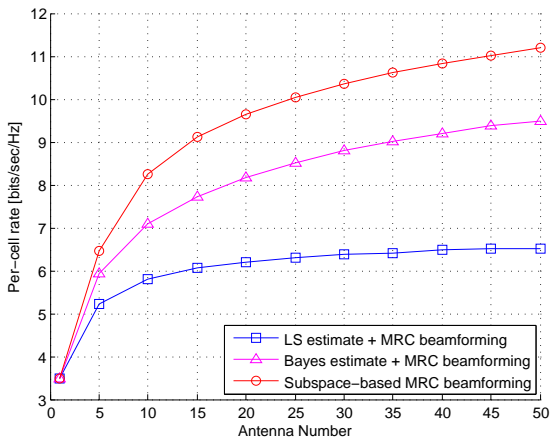


FIGURE: Per-cell rate vs. antenna number, uniformly distributed AOA with $\theta_{\Delta} = 30$ degrees, 2-cell network.

- Massive MIMO leads to strongly subspace structured covariances
- subspace orthogonality can be exploited for pilot decontamination, beamforming design, feedback reduction
- Orthogonality can be boosted with the help of coordinated pilot assignment and user scheduling
- Open issues: estimation of covariance matrices, random antenna arrays, dealing with skyscraper effects ...